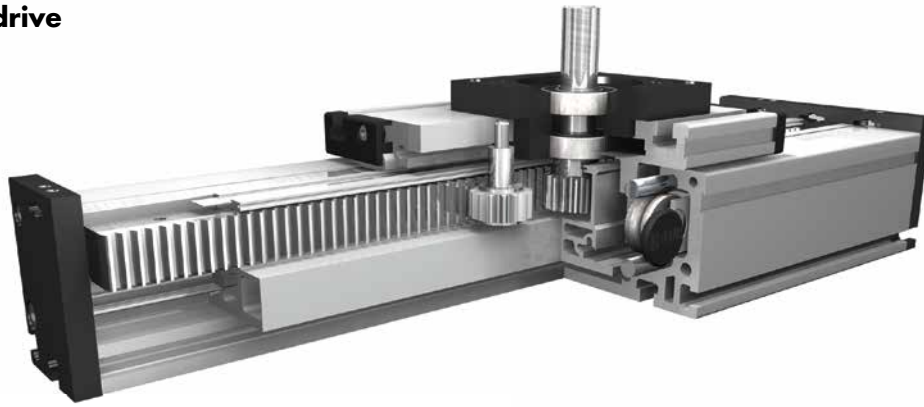


## Rack and pinion drive



### Function:

This unit consists of a rectangular aluminium profile with 2 integrated roller guides. The carriage, which has internal linear ball bearings that can be adjusted free of play, is driven along the guide rods by a high precision rack. The rack and pinion system is suitable for highly dynamic servo operation and ideal for lifting movements. The pinion is equipped with maintenance-free ball bearings. The rack is lubricated by a toothed felt wheel.

**Fitting position:** As required. Max. length 6.000 mm without joints.

**Carriage mounting:** By T-slots.

**Unit mounting:** By T-slots and mounting sets. The linear axis can be combined with any T-slot profile.

**Rack:** 6h23 Modul 2 (hardened and ground), repeatability ± 0,1 mm.

**Carriage support:** In the standard version, the carriage runs on 8 rollers which can be adjusted and serviced at a central servicing position. For longer carriages the number of rollers can be increased.

8.1

Forces and torques	Size	160		200	
	Forces/Torques	static	dynam.	static	dynam.
	$F_x$ (N)	1900	1800	4000	3800
	$F_y$ (N)	3000	2000	4400	3100
	$F_z$ (N)	3500	2800	4900	4400
	$M_x$ (Nm)	400	320	600	510
	$M_y$ (Nm)	360	300	560	480
	$M_z$ (Nm)	180	150	310	275
	<b>All forces and torques related to the following:</b> existing values $\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$ table values				
<b>No-load torque</b>					
	Nm	1,5		2,6	
<b>Speed</b>					
	(m/s) max	3		5,0	
<b>Tensile force</b>					
	permanent (N)	1900		3000	
<b>Geometrical moments of inertia of aluminium profile</b>					
	$I_x$ mm <sup>4</sup>	22,2x10 <sup>5</sup>		63,8x10 <sup>5</sup>	
	$I_y$ mm <sup>4</sup>	122,0x10 <sup>5</sup>		335x10 <sup>5</sup>	
	Elastic modulus N/mm <sup>2</sup>	70000		70000	

For life-time calculation of rollers use our homepage.

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

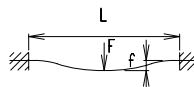
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- $S_i$  = safety factor 1,2 ... 2
- $M_n$  = no-load torque (Nm)
- n = rpm pulley (min<sup>-1</sup>)
- $M_o$  = driving torque (Nm)
- $P_o$  = motor power (KW)

Deflection:

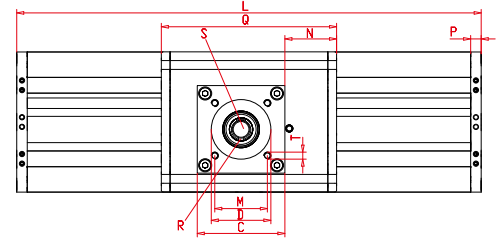
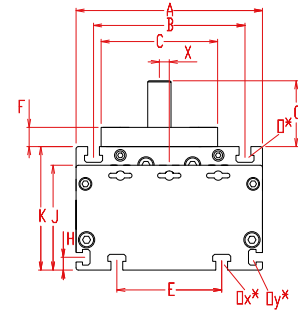
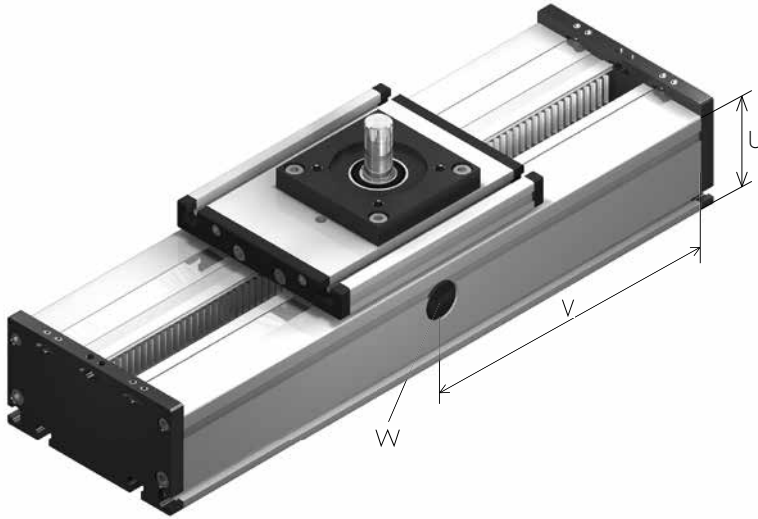
$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm<sup>2</sup>)
- I = second moment of area (mm<sup>4</sup>)



# Positioning system DLZA 120, 160, 200

Dimensions (mm)



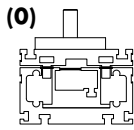
V = Q + 100 mm  
W = servicing position

\*For slide nuts refer to chapter 2.2 page 2

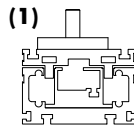
Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	B	C	D ±0,05	E	F	G	H	J	K	M	N	O for	Ox for	Oy for	P	Q	T for	U	X	Basic weight	Weight per 100 mm
DLZA 160	240	160	130	100	68	90	16,5	56,5	11	90	106	60	59	M 8	M 8	M 6	12	200	M 8	80	8,5	13,0 kg	2,10 kg
DLZA 200	320	200	160	120	90	140	20	45	15	110	129	80	95	M 10	M 10	M 8	15	270	M 8	100	5	28,9 kg	6,15 kg

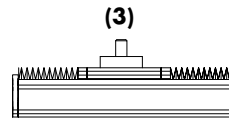
## 0 Choice of guide body profile:



(0) internal profile with cover bands



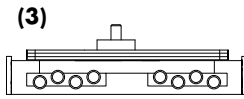
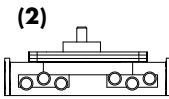
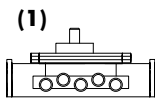
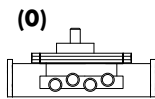
(1) internal profile without cover bands



(3) with bellows

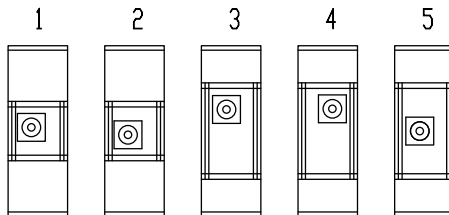
**Stainless versions upon request.**

## 0 Choice of carriage:



Size	Version 0		Version 1		Version 2		Version 3	
	Q	L	Q	L	Q	L	Q	L
160	200	240	250	290	>300	>340	-	-
200	270	320	330	380	>410	>460	>535	>580

## 1 Drive version:



## Shaft dimensions

Size	Shaft	Key	Pinion	
	∅ h6 x length		mm/rev.	Modul
160	20 x 40	6x6x35	100,53	2
200	18 x 25	6x6x20	94,25	2

DLZA 160 1 0 0 1 0 0 1 01500 — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

DLZA160 with internal profile and cover bands, standard carriage, 1260 mm stroke.