

Positioning system CLLZ 60

Belt drive

Special positioning system for building 3D printers and tripods.



Function:

The guide body consists of an aluminium profile with elegantly rounded outer edges, with a roller guide integrated into it. The carriage is moved by means of a revolving interior timing belt. At the front face there is a timing belt deflection unit with integrated coupling claws on two sides. The opposite front face is provided with a plate containing a tensioning device for the timing belt.

Fitting position:

As required. Max. length 6.000 mm without joints.

Carriage mounting:

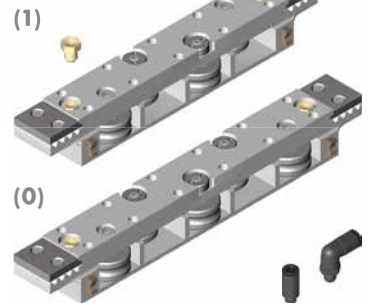
By tapped holes.

Belt performance:

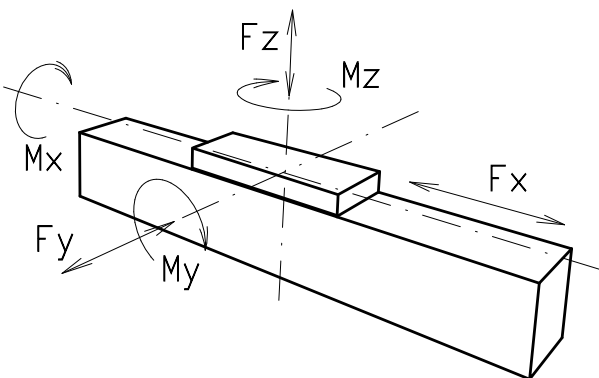
HTD with steel reinforcement, no backlash when changing direction, repeatability ± 0,1 mm.

Carriage support:

The carriage runs on 5 rollers which can be adjusted and serviced at each central servicing position. Two grease nipples at the carriage enable relubrication of the positioning system.



Forces and torques



Size	60	
	static	dynamic
Forces/Torques		
F_x (N)	1073	960
F_y (N)	780	650
F_z (N)	1170	845
M_x (Nm)	20	13
M_y (Nm)	78	65
M_z (Nm)	52	39
All forces and torques related to the following:		
existing values	$\frac{F_y}{F_{y_{dyn}}} + \frac{F_z}{F_{z_{dyn}}} + \frac{M_x}{M_{x_{dyn}}} + \frac{M_y}{M_{y_{dyn}}} + \frac{M_z}{M_{z_{dyn}}} \leq 1$	
table values		
No-load torque		
Nm	0,6	
Speed		
(m/s) max	4	
Tensile force		
permanent (N)	1050	
0,2 s (N)	1150	
Geometrical moments of inertia of aluminium profile		
I_x mm ⁴	4,47x10 ⁵	
I_y mm ⁴	5,59x10 ⁵	
Elastic modulus N/mm ²	70000	

For life-time calculation of rollers use our homepage · www.bahr-modultechnik.com

Driving torque:

$$M_o = \frac{F \cdot P \cdot S_i}{2000 \cdot \pi} + M_n$$

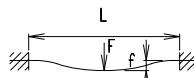
$$P_o = \frac{M_o \cdot n}{9550}$$

- F = force (N)
- P = pulley action perimeter (mm)
- S_i = safety factor 1,2 ... 2
- M_n = no-load torque (Nm)
- n = rpm pulley (min⁻¹)
- M_o = driving torque (Nm)
- P_o = motor power (KW)

Deflection:

$$f = \frac{F \cdot L^3}{E \cdot I \cdot 192}$$

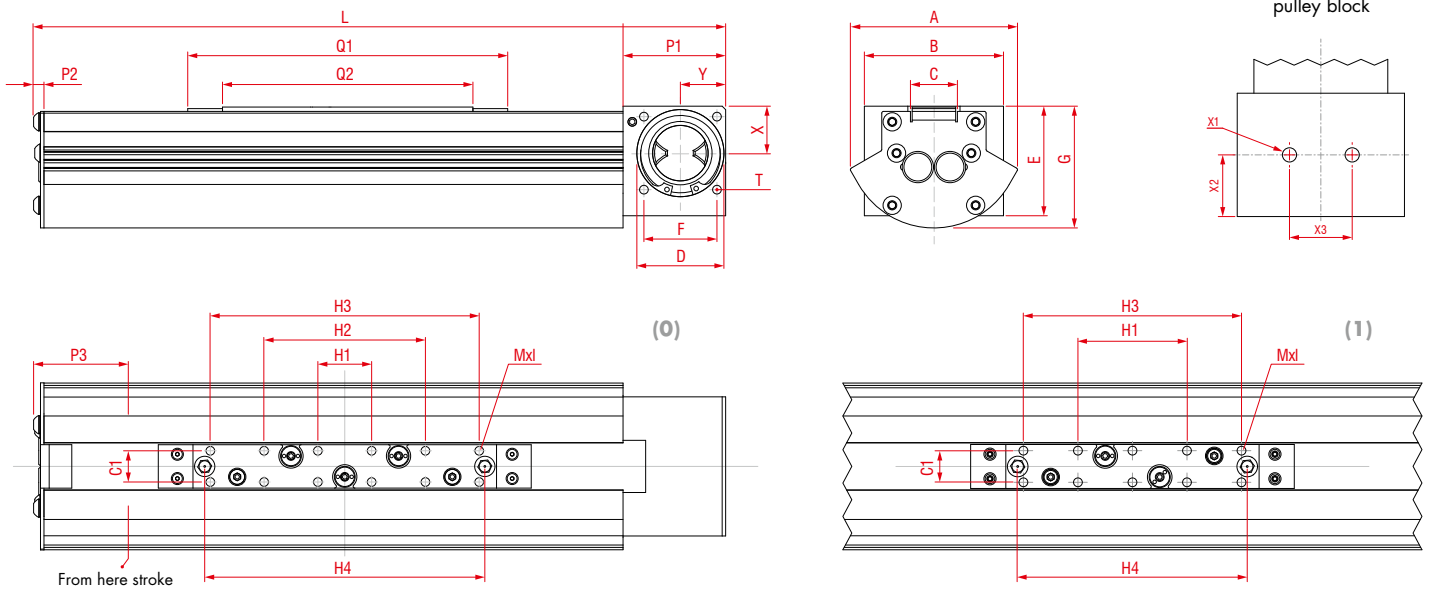
- f = deflection (mm)
- F = load (N)
- L = free length (mm)
- E = elastic modulus 70000 (N/mm²)
- I = second moment of area (mm⁴)



13.1

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Dimensions (mm)



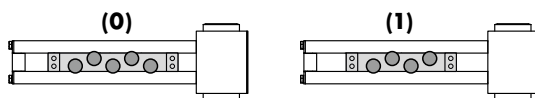
Size	X1	X2	X3
CLLZ 60	M8	29,5	30

Size	Basic length L	A	B	C	C1	D	E	F Ø	G	H1	H2	H3	H4	Mxl	P1	P2	P3	Q1	Q2	T	X	Y	Basic weight	Weight per 100 mm
CLLZ 60	329	97	80	25	18	47	63	42	70	31	93	155	161,5	M6x6	59	6	55	215	175	M6	27	26	2,65 kg	0,81 kg

0 Choice of guide body profile:

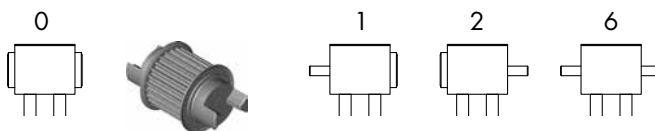
- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

0 Choice of carriages:



Carriage	L	Q1	Q2	H1	H2	H3	H4
60 Vers. (0)	330	215	175	31	93	155	161,5
60 Vers. (1)	299	184	144	62	—	124	130,5

0 Drive version:



Belt table:

Code No.	Size	Belt	mm/rev.	Number of teeth
0 3	60	5M 30	130	26

Shaft dimensions / Coupling claw:

Size	Shaft	Feather key	Coupling
60	14 h6 x 35	5x5x28	14

CLLZ 60 1 0 0 0 0 3 1 01500 — Basic length + stroke = total length

Pos. 1 2 3 4 5 6 7

Sample ordering code:

CLLZ60, standard body profile, double-sided coupling claw, 1329 mm stroke

