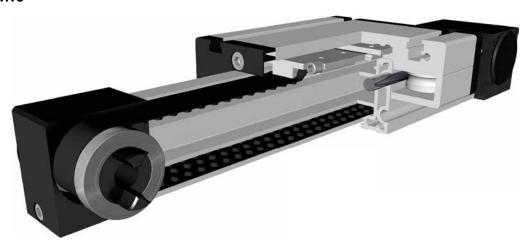
60 S

5,21x10<sup>5</sup>

70000

# Positioning system MLN 60, 60S

#### **Nubbed belt drive**



#### **Function:**

The guide body consists of an aluminium square profile with lateral, parallel, form-fit, internal hardened steel rods. The guide carriage, which is driven along the shafts by a nobbed belt, moves on the guide body with internal linear ball bearings that are adjustable free of play. The advantage of this system: The belt is guided within the profile, so that the system is independent of the mounting position. The nobbed belt is self-tracking and has a very low operating noise level thanks to its nobs being offset by 45°. Furthermore, it is almost vibration-free in the transition sections.

Size

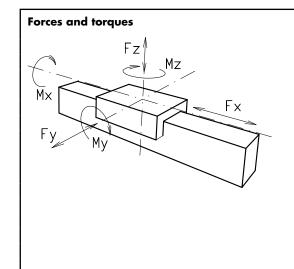
As required, max. length 6.000 mm without joints. Fitting position:

Carriage mounting: By T-slots.

**Unit mounting:** 

By T-slots or tapped holes in the bearing block, mounting sets.

**Belt type:** N10 with steel reinforcement, no backlash when changing direction, repeatability:  $\pm 0.1$  mm.



Forces	/Torques	static	dynamic	static	dynamic	
F	: <sub>x</sub> (N)	1950	1300	1950	1300	
F	: (N)	3000	2000	4100	3100	
F	-, (N)	1 <i>7</i> 00	1100	2160	1600	
Μ	, (Nm)	67	43	88	65	
Μ	(Nm)	90	70	190	140	
Μ	, (Nm)	120	100	230	1 <i>7</i> 0	
All forces and tor	ques relate to the f	ollowing:				
existing values	<u>Fy</u> + <u>Fz</u> +	Mx . My	. Mz	i		
table values	Fy <sub>dyn</sub> Fz <sub>dyn</sub>	$Mx_{dyn}$ $My_{dyn}$	- <b>+</b> — ≤1 Mz <sub>dyn</sub>	l		
No-load torque		1				
-	Nm	C	),6	(	),7	
Speed		,				
(m/	/s) max		5	7		
Tensile force		•				
perm	anent (N)	10	)50	](	050	
0,:	2 s (N)	11	50	1150		
Geometrical mom	ents of inertia of a	luminium profi	le			
Į	mm <sup>4</sup>	4,67	7x10 <sup>5</sup>	4,6	7x10 <sup>5</sup>	

For life-time calculation of rollers use our homepage.

5,21x10<sup>5</sup>

70000

Driving torque:

$$M_a = \frac{F * P * S_i}{2000 * \pi} + M_n$$

$$P_a = \frac{M_a * n}{9550}$$

= force = pulley action perimeter = safety factor 1,2 ... 2

 $M_n = \text{no-load torque}$ = rpm pulley

M<sub>a</sub> = driving torque = motor power

(N) (mm) (Nm)(min-1) (Nm) (KW)

Deflection: E\*I\*192 f = deflection(mm) F = loadL = free length (mm) E = elastic modulus 70000  $(N/mm^2)$ I = second moment of area  $(mm^4)$ 

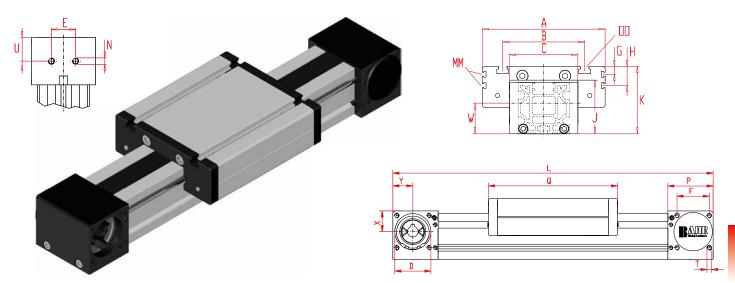
l, mm<sup>4</sup>

E-Modulus N/mm<sup>2</sup>









\*For slide nuts refer to chapter 2.2 page 2

Increasing the carriage length will increase the basic length by the same amount.

Size	Basic length L	A	В	С	<b>D</b> - 0,05	E	F	J	К	N	OO for	P	ø	T	υ	w	х	Y	Basic weight	Weight per 100 mm
<b>MLN</b> 60	290	144	96	80	47	30	42	63	<i>7</i> 9	M 8	M 8	59	168	M 6	29,5	30	27	26	4,7 kg	0,6 kg
MLN 60S	315	170	108	80	47	30	42	63	83	M 8	M 8	59	194	M 6	29,5	30	27	26	5,7 kg	0,6 kg

## Choice of guide body profile:

- (0) Standard (2) corrosion-protected guide rods and screws
- (4) expanded corrosion-protected version (depending on the availability of components)

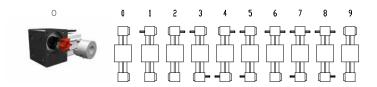
## **Choice of carriages:**





Size	Version 1					
Size	Q	L				
60	184	306				
605	214	336				

# O Drive version:



Version 9 is the same as 0, but with double sided coupling claw.

The standard version is supplied without shaft.

#### Belt table

Code No.		Size	Belt	mm/rev.	Number of teeth					
0	8	60 (S)	Nobbed belt N10	130	13/3					

#### Shaft dimensions / Coupling claw

Size	<b>Shaft</b> ø hó x length	Key	Coupling		
60 (S)	14 x 35	5x5x28	14		

MLN 60 1 0 0 0 0 8 1 01500

Basic length + stroke = total length

For combination kits and connecting elements refer to chapter 2.2

Sample ordering code:

MLN 60, standard body profile, standard carriage, drive version 0, knobbelt belt, 1210 mm stroke







