FORM **ROTARY TABLES CR / TH** [ED. 01].

Company _____

Email _____

Phone _____

WEISS

Please fill out the following questionnaire carefully so we can select the right product for you. Please note that we can only guarantee the best choice for you if all information is completely available. If important information is missing, we will contact you. You can complement this information with photographs, 3D files, etc.

Model

☐ TH 400F   ☐ CR 300E   ☐ CR 1000C

☐ TH 700F   ☐ CR 400E   ☐ CR 1300C

☐ TH 1000F   ☐ CR 500E   ☐ CR 2000C

             ☐ CR 700C

Colour of the gearbox

☐ RAL 7035 [light grey]

☐ Special colour RAL [extra charge] _____

Additional baseframe (optional)

☐ for all CR / TH models

Indexing time

Based on the calculated mass moment of inertia, do you require:

☐ The shortest indexing time _____

☐ A longer indexing time of approx. [sec.] _____

☐ Angle of rotation [º] _____

☐ Standing time [sec.] _____

REQUIRED TO SPECIFY YOUR CR / TH TABLE   **MANDATORY FILLING**

The following specification regarding your configuration is fundamental for your calculation of the mass moment of inertia.

Additional indexing plate

Diameter [mm] _____   Thickness [mm] _____   Number of stations _____

Material ☐ Al   ☐ St   ☐ Other   Weight per station [kg] _____

☐ Included in the delivery   ☐ Don't provide   Diameter of the center of gravity [mm] _____

Please forward a sketch detailing the load distribution on the table.   Part Dimensions   x ☐/y   x _____ y _____

Total mass moment of inertia [kg m²] (additional indexing plate and add-ons) _____

Electrical data

☐ WEISS control package

Servo motor, amplifier, W.A.S. Software

Cables length: ☐ 5m ☐ 10m ☐ 15m ☐ 20m ☐ 25m

☐ Hand-held terminal (optional)

Interface to the customer PLC

☐ Ethernet   ☐ Profibus-DP

☐ digitale I/O   ☐ CAN Bus

☐ Free ASCII protocol ☐ DeviceNet (Rockwell)

☐ Ethernet/IP (Rockwell) ☐ Modbus TCP (Telemecanique)

Interface to W.A.S. – WEISS Application Software

RS232 and Ethernet are included in the scope of delivery

☐ Converter USB to RS232

☐ Supply of customers motor and controller ***

☐ Customer to fit motor ***

Manufacturer: _____

Type: _____

*** Please forward a drawing of motor flange